

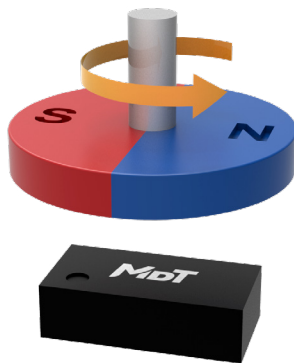
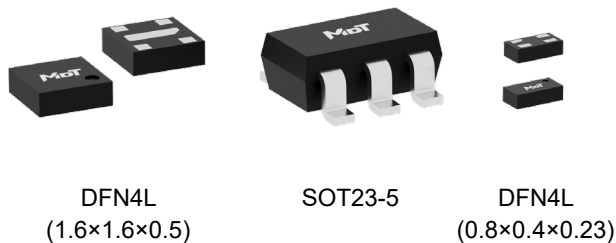
TMR3017

High Accuracy Analog TMR Angle Sensor

Description

TMR3017 contains a push-pull Wheatstone bridge, which is composed of four high-sensitivity tunneling magnetoresistance (TMR) elements. The sensor outputs a sinusoidal signal, and the period of the signal is that the direction of the magnetic field rotates 360° in the sensing plane.

TMR3017 is available in three compact SOT23-5, DFN4L (0.8 mm × 0.4 mm × 0.23 mm) and DFN4L (1.6 mm × 1.6 mm × 0.5 mm) package for easy assembly in small spaces.

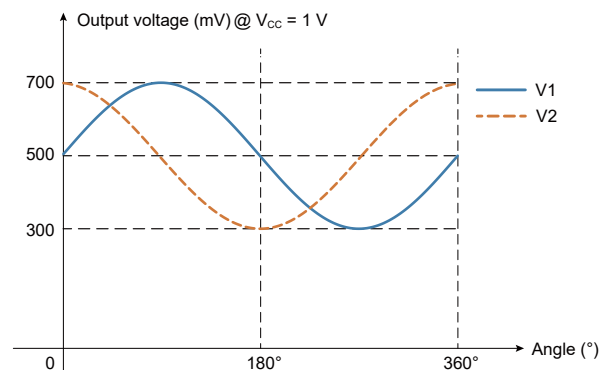


Features and Benefits

- Tunneling magnetoresistance (TMR) technology
- Wide range supply voltage
- Analog differential output
- Excellent temperature stability
- Adapt to large air gap
- Compact DFN package
- RoHS and REACH compliant

Applications

- Angular position sensing
- Linear position sensing



Selection Guide

Part Number	Output	Supply Voltage	Operating Temperature	Package	Packing Form
TMR3017D	Analog	≤ 5.5 V	-30 °C to 125°C	DFN4L (0.8×0.4×0.23)	Tape & Reel
TMR3017BF	Analog	≤ 5.5 V	-30 °C to 125°C	DFN4L (1.6×1.6×0.5)	Tape & Reel
TMR3017S	Analog	≤ 5.5 V	-30 °C to 125°C	SOT23-5	Tape & Reel

Catalogue

1. Functional Block Diagram.....	03
2. Pin Configuration	03
3. Absolute Maximum Ratings	04
4. Electrical Specifications.....	04
5. Magnetic Specifications.....	04
6. Specification Definitions	05
7. Applications	06
8. Dimensions.....	07

1. Functional Block Diagram

TMR3017 TMR angle sensor integrates a Wheatstone bridge using TMR elements to increase the output amplitude and improve the temperature characteristics.

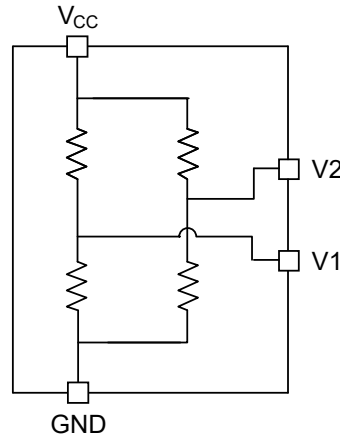


Figure 1. Block diagram

2. Pin Configuration

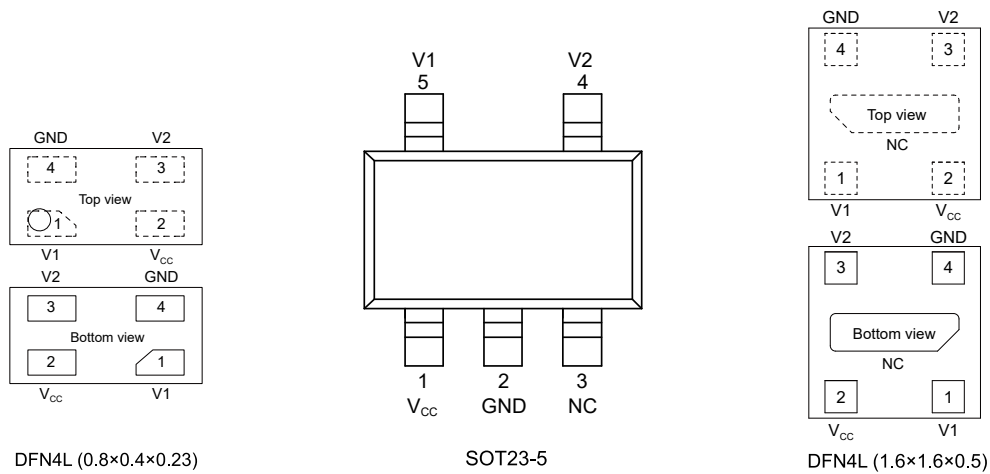


Figure 2. Pin configuration

Number			Name	Function
DFN4L (0.8x0.4)	DFN4L (1.6x1.6)	SOT23-5		
1	1	5	V1	Output signal 1
2	2	1	V _{CC}	Power supply
3	3	4	V2	Output signal 2
4	4	2	GND	GND
-	5	3	NC	NC

3. Absolute Maximum Ratings

Parameters	Symbol	Min.	Max.	Unit
Supply voltage	V_{CC}	-	6	V
Magnetic flux density	B	-	3000	Gs
ESD performance (HBM)	$V_{ESD(HBM)}$	-	3000	V
ESD performance (CDM)	$V_{ESD(CDM)}$	-	2000	V
Operating ambient temperature	T_A	-30	125	°C
Storage ambient temperature	T_{STG}	-40	125	°C

Note: The absolute maximum rating only lists the conditions under which the sensors are not permanently damaged. For normal operations please refer to Specifications.

4. Electrical Specifications

$V_{CC} = 1.0\text{ V}$, $T_A = 25\text{ °C}$

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
Supply voltage	V_{CC}	operating	-	-	5.5	V
Bridge resistance	R_B	$B = 300\text{ Gs}$	100	200	300	k Ω
Peak voltage	V_{PEAK1}, V_{PEAK2}	$B = 300\text{ Gs}$	150	200	250	mV/V
Peak-to-peak voltage	V_{PP1}, V_{PP2}	$B = 300\text{ Gs}$	300	400	500	mV/V
Midpoint voltage	V_{Mid}	$B = 300\text{ Gs}$	450	500	550	mV/V
Offset voltage	V_{OFFSET}	$B = 300\text{ Gs}$	-15	0	15	mV/V
Temperature coefficient of bridge resistance	TCR_B	-	-	-0.05	-	%/°C
Temperature coefficient of amplitude	TCV_{PEAK}	-	-	-0.09	-	%/°C

5. Magnetic Specifications

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
Magnetic flux density	B	-	200	-	800	Gs

Note: 1 Gauss in air = 0.1 millitesla = 79.8 A/m

6. Specification Definitions

6.1 Bridge resistance R_B

Resistance between pin V_{CC} and GND

6.2 Output amplitude V_{PEAK}

$$V_{PEAK1} = \frac{V_{MAX1} - V_{MIN1}}{2} \quad V_{PP1} = V_{MAX1} - V_{MIN1}$$

$$V_{PEAK2} = \frac{V_{MAX2} - V_{MIN2}}{2} \quad V_{PP2} = V_{MAX2} - V_{MIN2}$$

6.3 Midpoint voltage V_{Mid}

$$V_{Mid1} = \frac{V_{MAX1} + V_{MIN1}}{2}$$

$$V_{Mid2} = \frac{V_{MAX2} + V_{MIN2}}{2}$$

6.4 Offset V_{OFFSET}

$$V_{OFFSET} = V_{Mid1} - V_{Mid2}$$

6.5 Temperature coefficient of bridge resistance TCR_B

R_H : High temperature resistance R_L : Low temperature resistance R_N : Resistance at 25°C

T_H : High temperature T_L : Low temperature T_N : 25°C

$$TCR_B = \frac{R_H - R_L}{R_N (T_H - T_L)} \times 100\%$$

6.6 Temperature coefficient of amplitude TCV_{PEAK}

V_{PEAKH1} : V_{OUT1} in high temp V_{PEAKL1} : V_{OUT1} in low temp V_{PEAKN1} : V_{OUT1} at 25°C

V_{PEAKH2} : V_{OUT2} in high temp V_{PEAKL2} : V_{OUT2} in low temp V_{PEAKN2} : V_{OUT2} at 25°C

T_H : High temperature T_L : Low temperature T_N : 25°C

$$TCV_{PEAK1} = \frac{V_{PEAKH1} - V_{PEAKL1}}{V_{PEAKN1} (T_H - T_L)} \times 100\% \quad TCV_{PEAK2} = \frac{V_{PEAKH2} - V_{PEAKL2}}{V_{PEAKN2} (T_H - T_L)} \times 100\%$$

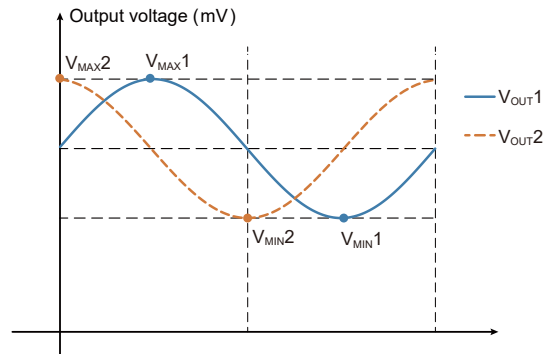


Figure 3. Definition of V_{MIN} and V_{MAX} in output signal

7. Applications

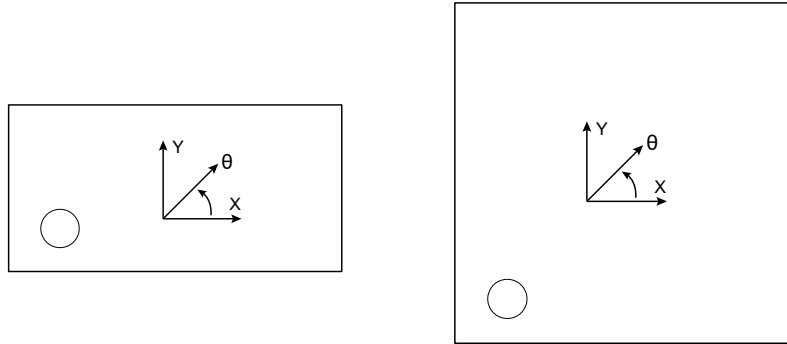


Figure 4-1. Sensing direction (DFN4L)

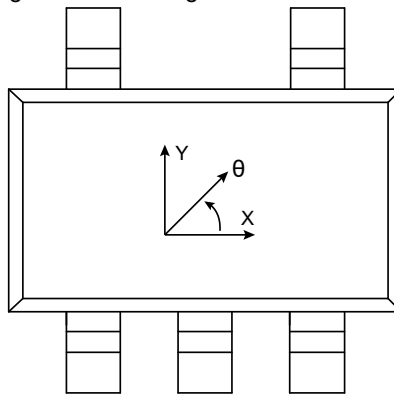


Figure 4-2. Sensing direction (SOT23-5)

The sensing direction is parallel to the X-Y plane where package laser mark is located as shown in Figure 4. When the sensor is in an appropriate magnetic field, the resistance value of each TMR element of the sensor changes due to the difference between the sensitive direction of each TMR element and the direction of the magnetic field, resulting in a corresponding change in the output voltage.

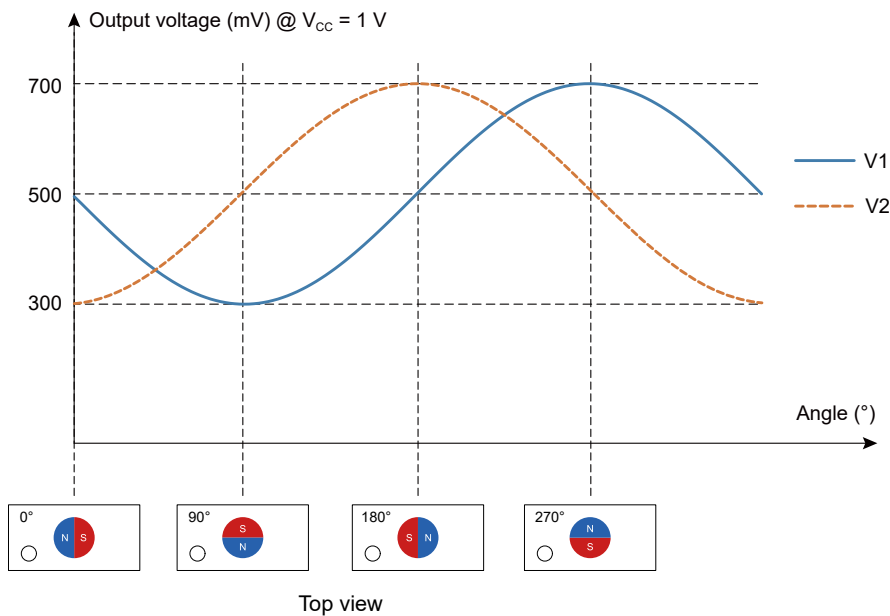


Figure 5-1. Single-ended output of TMR3017D in one period @ $V_{CC} = 1\text{ V}$

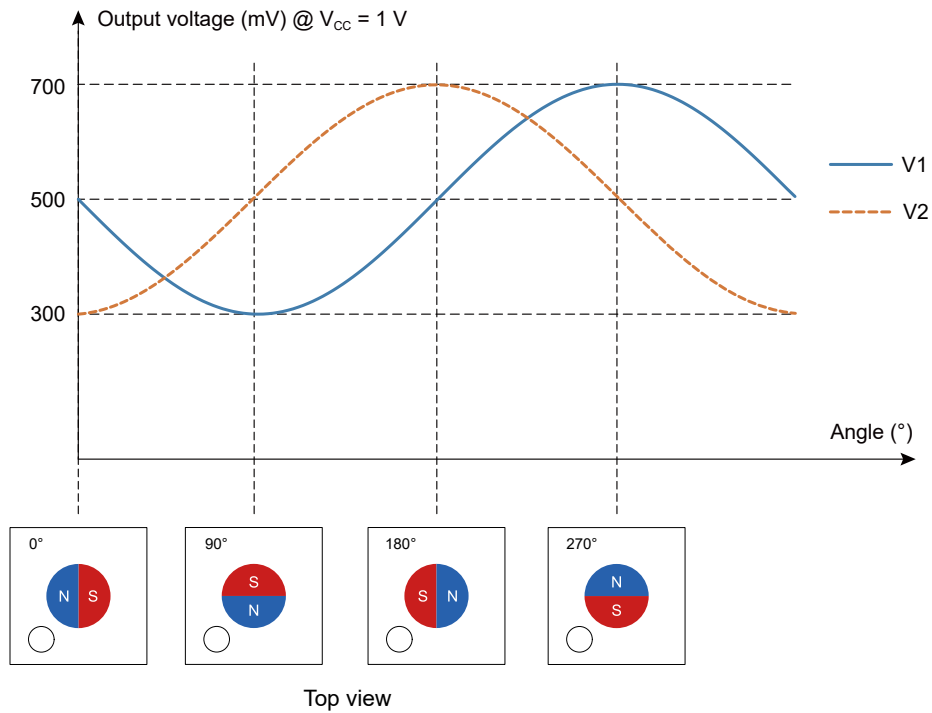


Figure 5-2. Single-ended output of TMR3017BF in one period @ $V_{CC} = 1\text{ V}$

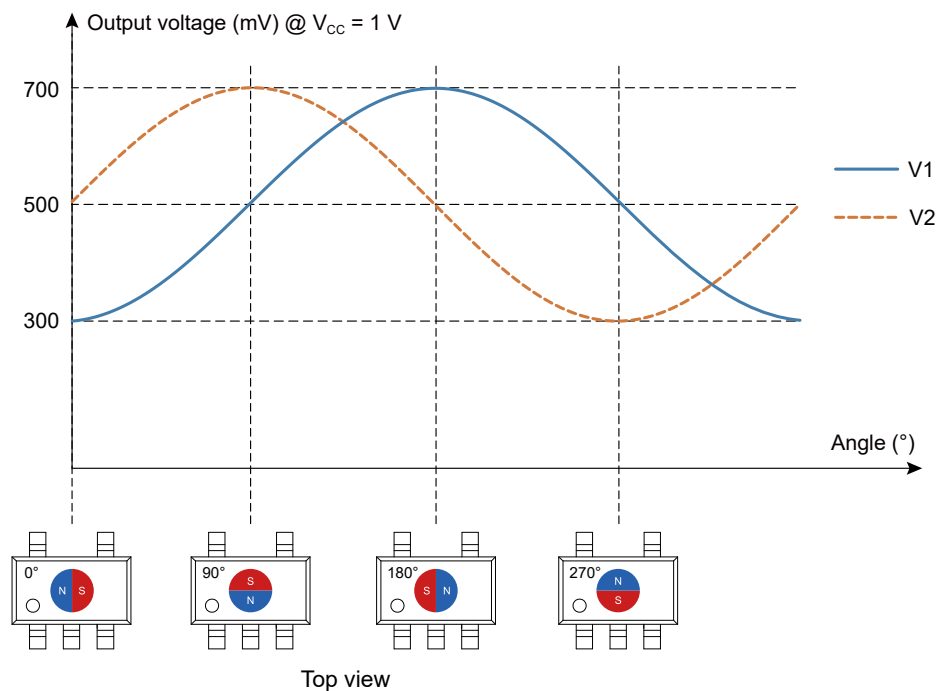


Figure 5-3. Single-ended output of TMR3017S in one period @ $V_{CC} = 1\text{ V}$

8. Dimensions

DFN4L (0.8×0.4×0.23) Package

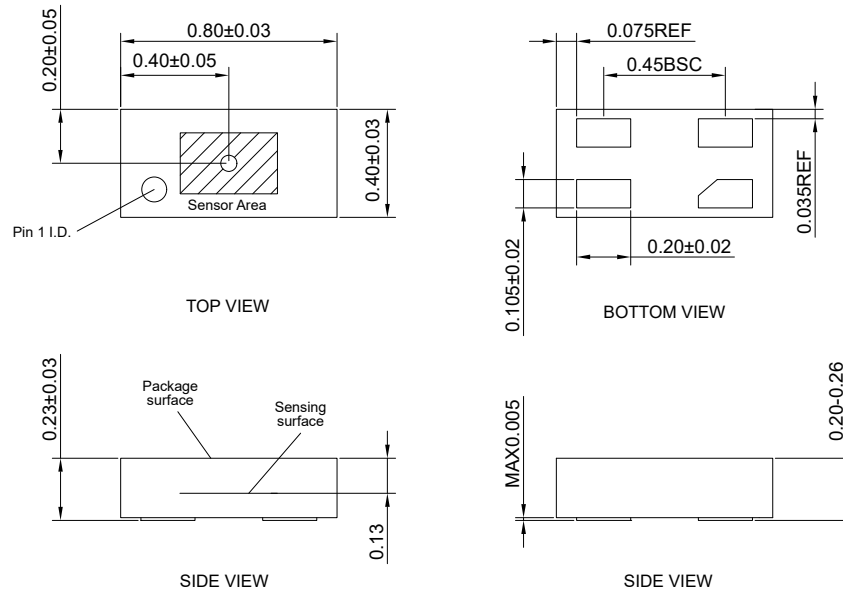


Figure 6. Package outline of DFN4L(0.8×0.4×0.23) (unit: mm)

DFN4L (1.6×1.6×0.5) Package

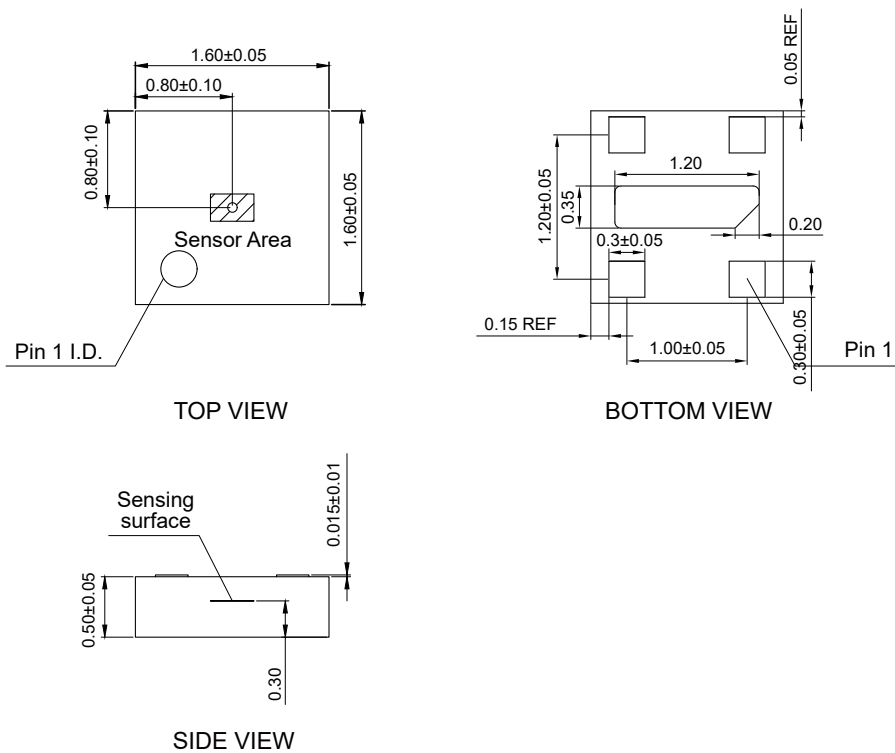


Figure 7. Package outline of DFN4L(1.6×1.6×0.5) (unit: mm)

SOT23-5 Package

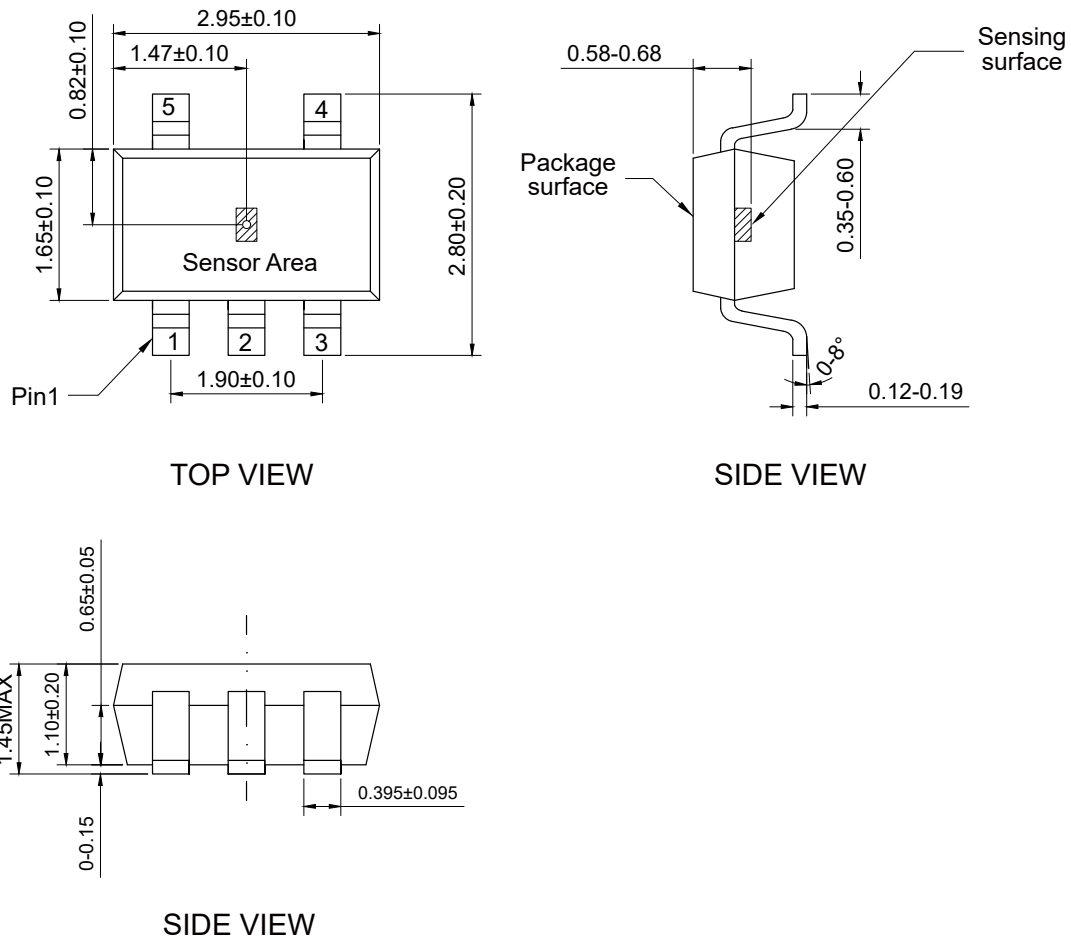


Figure 8. Package outline of SOT23-5 (unit: mm)

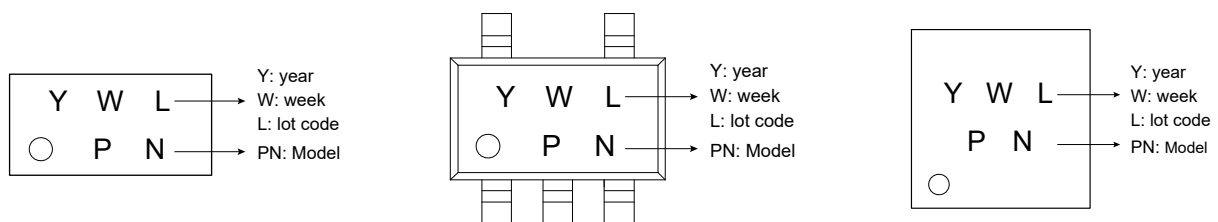
Product Marking Description

“Y” represents the year of material input, with one character for every half year, and 26 characters covering 13 years;

“W” represents the week of material input, with 26 letters representing 26 weeks;

“L” represents the batch of material input, with one character for each wafer per input;

“PN” represents the part number.



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