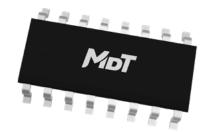


# **AMR2302**

## High Accuracy, Low Noise Dual Axis Linear Magnetic Sensor

### **Description**

The AMR2302 linear sensor utilizes two push-pull Wheatstone bridges each composed of four highly sensitive AMR sensor elements. These Wheatstone bridges effectively compensate the sensor's temperature drift to achieve outstanding temperature stability with minimal noise. AMR2302 is available in the SOP16 package.



SOP16

#### Features and Benefits

- Anisotropic magnetoresistance (AMR) technology
- Low noise density: 300 pT/√Hz@1 Hz
- · Wide range supply voltages
- · Low saturation field
- · Excellent temperature stability
- · Low hysteresis
- · RoHS & REACH compliant

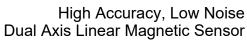
### **Applications**

- · Weak magnetic field sensing
- · Current sensor
- · Position sensor
- Magnetometer

#### Selection Guide

Part Number	Linear Range	Sensitivity	Set/reset Coil Resistance	Offset Coil Resistance	Noise Density	Package	Packing Form
AMR2302P	±3 Gs	0.9 mV/V/Gs	5 Ω	45 Ω	300 pT/√Hz	SOP16	Tape & Reel







## Catalogue

1. Functional Block Diagram	03
2. Sensing Direction	03
3. Pin Configuration	03
4. Absolute Maximum Ratings	04
5. Electrical Specifications	04
6. Typical Output Characteristics	05
7. Application Information	06
8. Dimensions	07



## 1. Functional Block Diagram

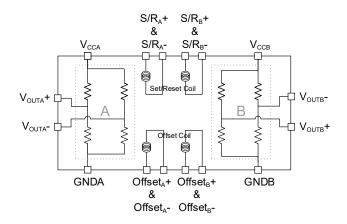


Figure 1. Block Diagram

### 2. Sensing Direction

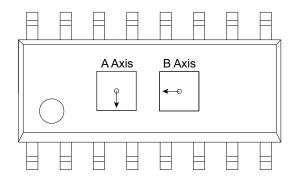


Figure 2. Sensing Direction (SOP16)

## 3. Pin Configuration

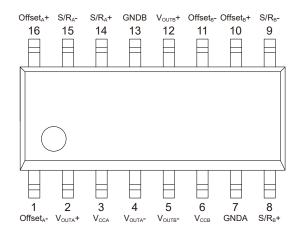


Figure 3. Pin Configuration (SOP16)

Pin Number	Name	Function		
1	Offset <sub>A</sub> -	A axis offset voltage -		
2	V <sub>OUTA</sub> +	A axis output +		
3	V <sub>CCA</sub>	A axis supply voltage		
4	V <sub>OUTA</sub> -	A axis output -		
5	V <sub>OUTB</sub> -	B axis output -		
6	V <sub>CCB</sub>	B axis supply voltage		
7	GNDA	A axis ground		
8	S/R <sub>B</sub> +	B axis set/reset input+		
9	S/R <sub>B</sub> -	B axis set/reset input -		
10	Offset <sub>B</sub> +	B axis offset voltage +		
11	Offset <sub>B</sub> -	B axis offset voltage -		
12	V <sub>OUTB</sub> +	B axis output +		
13	GNDB	B axis ground		
14	S/R <sub>A</sub> +	A axis set/reset input +		
15	S/R <sub>A</sub> -	A axis set/reset input -		
16 Offset <sub>A</sub> +		A axis offset +		



## 4. Absolute Maximum Ratings

Parameters	Symbol	Min.	Max.	Unit	
Supply Voltage	V <sub>cc</sub>	-	12	V	
ESD Performance (HBM)	$V_{ESD}$	-	4	kV	
Operating Ambient Temperature	T <sub>A</sub>	-55	150	°C	
Storage Ambient Temperature	T <sub>STG</sub>	-55	175	°C	
Soldering Temperature	T <sub>i</sub>	-	260	°C	
Magnetic Field	В	-	10000	Gs	

## 5. Electrical Specifications

 $V_{\rm CC}$  = 5.0 V,  $T_{\rm A}$  = 25 °C,  $I_{\rm S/R}$  = 1.5 A, dual differential output unless otherwise specified

Parameter Symbol		Condition	Min.	Тур.	Max.	Unit
Supply Voltage	V <sub>CC</sub>	Bridge voltage, referenced to ground	1.8	5	12	V
Bridge Resistance	R <sub>B</sub>	I = 5 mA	600	650	1100	Ω
Field Range	B <sub>SAT</sub>	Full scale (FS)	-6	-	6	Gs
	NONL	Fit in: ±1 Gs	-	0.05	-	%FS
Linearity Error		Fit in: ±3 Gs	-	0.15	-	
		Fit in: ±6 Gs	-	1.0	1.6	
Hysteresis Error	HYS	2 sweeps, across ±6 Gs	-	0.05	-	%FS
Repeatability Error	B <sub>repeat</sub>	2 sweeps, across ±6 Gs	-	0.08	-	%FS
Bridge Offset V <sub>OFFSET</sub>		$V_{OFFSET} = (V_{OUT}+) - (V_{OUT}-),$ B = 0 Gs, after set pulse	-10	±2	+10	mV/V
Sensitivity	SEN	-	0.6	0.9	1.1	mV/V/Gs
Voltage Noise Density	$V_{noise}$	At 1 Hz	-	25	-	nV/√Hz
Magnetic Noise Density	B <sub>noise</sub>	At 1 Hz	-	300	-	pT/√Hz
Resolution RES		Bandwidth = 10 Hz	-	40	-	μGs
Bandwidth	BW	Magnetic signal (lower limit = DC)	-	5	-	MHz
Offset Coil Resistance R <sub>OFFCOIL</sub>		Measured from OFFSET+ to OFFSET-	35	45	55	Ω
Offset Field	B <sub>OFFCOIL</sub>	Field applied in sensitive direction	4.0	5.0	7.0	mA/Gs
Set/Reset Coil Resistance R <sub>S/R</sub>		Measured between S/R+ and S/R-	3	5	7	Ω
Set/Reset Current I <sub>S/R</sub>		2 µs current pulse	1	1.5	5	Α
Disturbing Field B <sub>disturb</sub>		Sensitivity starts to degrade, restore by S/R pulse	-	20	-	Gs
Sensitivity Temperature Coefficient	TCS	T <sub>A</sub> = -40 °C to 125 °C	-	-3800	-	PPM/°C
Bridge Offset	тсо	$T_A$ = -40 °C to 125 °C, w/o set/reset	-	500	-	PPM/°C
Temperature Coefficient		T <sub>A</sub> = -40 °C to 125 °C, w/ set/reset	-	10	-	
Resistance Temperature Coefficient	TCR <sub>B</sub>	T <sub>A</sub> = -40 °C to 125 °C	-	2700	-	PPM/°C
Cross-Axis Effect	$X_{B}$	Cross field = 1 Gs	-	±0.5	-	%FS



### 6. Typical Output Characteristics

Figure 4 shows the response of the AMR2302 to an applied magnetic field. (Applied field =  $\pm 20$  Gs, analysis field =  $\pm 6$  Gs, and  $V_{CC} = 5$  V).

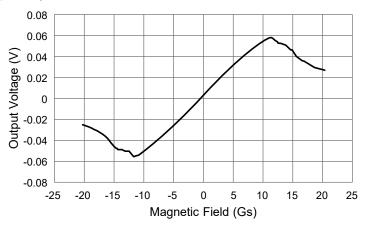


Figure 4. AMR2302 output vs. applied field

#### Typical voltage noise density

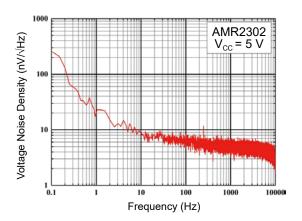


Figure 5. AMR2302 voltage noise density vs. frequency

#### Typical magnetic noise density

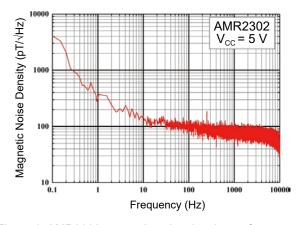


Figure 6. AMR2302 magnetic noise density vs. frequency

05



### 7. Application Information

A voltage pulse of 5 V for 2 µs in 10 kHz can be select as the set/reset signal. The pulse voltage, pulse width and duty cycle can be adjusted in a certain range. A typical drive circuit is shown in Figure 7.

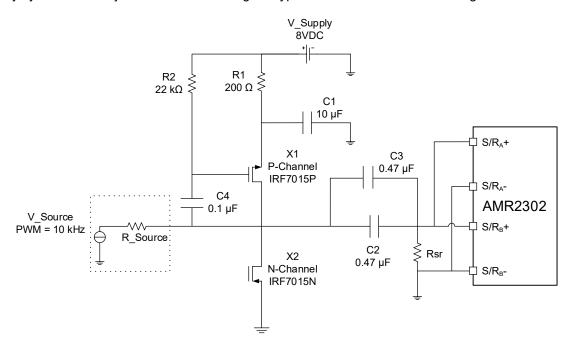


Figure 7. Set/reset drive circuit of AMR2302

The circuit will generate 5 V set/reset pulses, as illustrated in figure 8.

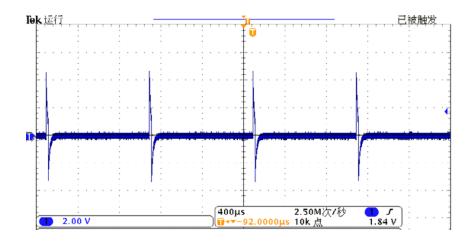
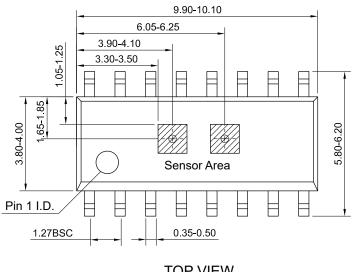


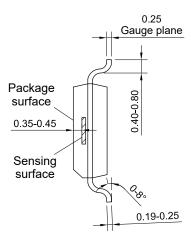
Figure 8. Set/reset voltage pulses waveform

When set-only or reset-only pulse is applied, the set- and reset- pulse is switchable by reversing the set/reset input.



## 8. Dimensions SOP16 Package





**TOP VIEW** 

SIDE VIEW

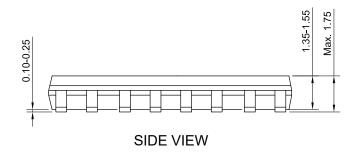


Figure 9. Package outline of SOP16 (unit: mm)

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